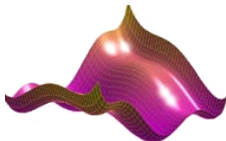


Polynomial Moment Optimization Database

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General online Julia training, POEMA
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Part I - The Polynomial-Moment data

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Install the Julia package

In Julia, type:

```
] add https://github.com/PolynomialMomentOptimization/PMO.jl
```

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```

To run the examples of this tutorial, you also need to install a package for multivariate polynomials:

```
] add DynamicPolynomials
```

Creating a github account and joining the project data

To create new data, you need a github account.

💡 Send a mail to `bernard.mourrain@inria.fr` with subject: `Joining PMO/data <your.github.id>`

💡 We add you in the github project

`https://github.com/PolynomialMomentOptimization/data`
to push data in the database.

💡 You can configure your git access (in julia or in a terminal):

```
; git config --global user.name "Firstname Lastname"  
; git config --global credential.helper store
```

What is in the database

The database contains the following types of data:

- Polynomial Optimization Programs (POP),
- Moment Optimization programs (MOM),
- Semi-Definite Programs (SDP)

These mathematical programs are described by

- an objective function (optional)
- sign constraints (optional)
- equality constraints (optional)

Polynomial data

$$\begin{aligned} \inf_{x \in \mathbb{R}^n} \quad & f(x) \\ \text{s.t.} \quad & g_1(x) \geq 0, \dots, g_s(x) \geq 0 \\ & h_1(x) = 0, \dots, h_t(x) = 0 \end{aligned}$$

where $f, g_j, h_i \in \mathbb{R}[x]$.

- f is the objective function,
- (g_j) are sign constraints,
- (h_i) are equality constraints.

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- f is the objective function,
- (g_j) are sign constraints,
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💡 Let's add this one:

$$\begin{aligned} \inf_{x,y} \quad & x^2y^2 + x^4 - y^3 \\ \text{s.t.} \quad & x^2 + \pi y^2 - 2 \leq 0 \\ & x \geq 0 \\ & 2y^2 - y = 0 \end{aligned}$$

Polynomial data: example

```
[1]: using PMO, DynamicPolynomials
```

```
X = @polyvar x y
f  = x^2*y^2+x^4-y^3
g1 = x^2 + Float64(pi)*y^2 -2
g2 = x
h1 = 2*y^2-y

F = PMO.polynomial((f, "inf"),
                   (g1, "<=0"),
                   (g2, ">=0"),
                   (h1, "=0"))

F["doc"]=
"""
A first polynomial example.
"""
```

Polynomial data: example

Alternative for the same data F:

```
[2]: F = PMO.data((f, "inf"),  
                 (g1, "<=0"),  
                 (g2, ">=0"),  
                 (h1, "=0") ; type = "polynomial")
```

Polynomial data: example

Alternative for the same data F:

```
[2]: F = PMO.data((f, "inf"),
                  (g1, "<=0"),
                  (g2, ">=0"),
                  (h1, "=0") ; type = "polynomial")
```

[2]: Optimisation model:

```
type => polynomial
variables => ["x", "y"]
nvar => 2
constraints => [ x^2 + 3.141592653589793*y^2 - 2.0
↳<=0, x >=0, 2*y^2 - y =0 ]
objective => inf x^4 + x^2*y^2 - y^3
version => 0.0.1
uuid => 89de08fc-9155-11eb-1bb2-3dc70c092fe5
```

Polynomial data: attributes

The data contains the following information:

- the type `P[:type]` specifying if it is a polynomial, moment or SDP program
- the variables `P[:variables]` as an array of strings
- the number of variables `P[:nvar]`
- the constraints `P[:constraints]` (optional)
- the objective function `P[:objective]` (optional)
- the version of the data `P[:version]`
- a universally unique identifier `P[:uuid]`

Attributes can be modified, e.g. `P[:version]= "0.0.2"`

New attributes can be added to the data, e.g. `P[:ref] = ["doi1", "doi2"]`.

Attributes can be removed, e.g. `P[:version]= nothing` (but this is not recommended)

Polynomial data: write & read

Print/save object of type PMOData in json format:

```
[3]: PMO.write(F)  
      PMO.write("tmp.json",F)
```

Polynomial data: write & read

Print/save object of type PMOData in json format:

```
[3]: PMO.write(F)
      PMO.write("tmp.json",F)
```

Read data \Rightarrow G of type PMOData, read from the json file, where F was saved (it writes in json as F):

```
[4]: G = PMO.read("tmp.json")
      PMO.write(G)
```

Moment data

$$\begin{aligned} \inf_{\mu_j} \quad & \langle \mu_1 | f_1 \rangle + \dots + \langle \mu_\nu | f_\nu \rangle \\ \text{s. t.} \quad & \sum_{j=1}^{\nu} g_{1,j} \star \mu_j \succeq 0, \dots, \\ & \sum_{j=1}^{\nu} h_{1,j} \star \mu_j = 0, \dots, \\ & \sum_{j=1}^{\nu} \langle \mu_j | l_{1,j} \rangle + l_{1,\nu+1} \geq 0, \dots, \\ & \sum_{j=1}^{\nu} \langle \mu_j | m_{1,j} \rangle + m_{1,\nu+1} = 0, \dots, \end{aligned}$$

where μ_j are moment sequences, i.e. elements of the dual $\mathbb{R}[x]^*$, $f_j, g_{i,j}, h_{i,j}, l_{i,j}, m_{i,j} \in \mathbb{R}[x]$, $l_{i,\nu+1}, m_{i,\nu+1} \in \mathbb{R}$.

The constraints $\sum_{j=1}^{\nu} \langle \mu_j | l_{i,j} \rangle \geq 0$, $\sum_{j=1}^{\nu} \langle \mu_j | m_{i,j} \rangle = 0$ are respectively mass sign constraints and mass equality constraints.

The product \star is defined as follows: for $p \in \mathbb{R}[x]$, $\mu \in \mathbb{R}[x]^*$,
 $p \star \mu : q \mapsto \langle p \star \mu | q \rangle := \langle \mu | pq \rangle$.

Moment data: example

💡 Let's add this one:

$$\begin{aligned} \inf_{\mu_1, \mu_2} \quad & \langle \mu_1 | x^2 y^2 + x^4 - y^3 \rangle + \langle \mu_2 | xy \rangle \\ \text{s.t.} \quad & (2 - x^2 - \pi y^2) \star \mu_1 \succeq 0 \\ & \langle \mu_2 | x \rangle - 1 \geq 0 \\ & \langle \mu_1 | 2y^2 - y \rangle + \langle \mu_2 | x^2 + 2.1xy^2 \rangle - 2 = 0 \end{aligned}$$

Moment data: example

```
[5]: using DynamicPolynomials, PMO
      @polyvar x y
      f1 = x^2*y^2+x^4-y^3
      f2 = x*y

      g1 = 2 -x^2 - Float64(pi)*y^2
      g2 = x

      h1 = 2*y^2-y
      h2 = x^2+y*2.1*x*y

      F = PMO.moment(( [f1,f2], "inf" ),
                    ( [g1,0], ">=0" ),
                    ( [0,g2,-1], ">=0 *" ),
                    ( [h1, h2], "=0 *" )
                    )
```

SDP data

$$\begin{aligned} \inf_{x \in \mathbb{R}^n} \quad & f^T x \\ \text{s.t.} \quad & \sum_{j=1}^n A_{1,j} x_j + A_{1,0} \succeq 0, \dots, \\ & \sum_{j=1}^n c_{1,1}^T x + d_{1,1} \geq 0, \dots, \\ & \sum_{j=1}^n c_{0,1}^T x + d_{0,1} = 0, \dots, \end{aligned}$$

where $f, c_{i,j} \in \mathbb{R}^n$, $d_{i,j} \in \mathbb{R}$, $A_{i,j} \in S^{n_i}$ are symmetric matrices of size n_i .

 Let's add this one:

$$\begin{aligned} \inf_{x_1, x_2, x_3} \quad & x_1 + 2x_2 + 3x_3 \\ \text{s.t.} \quad & \begin{pmatrix} 2 & -1 & 0 \\ -1 & 2 & 0 \\ 0 & 0 & 2 \end{pmatrix} x_1 + \begin{pmatrix} 2 & 0 & -1 \\ 0 & 2 & 0 \\ -1 & 0 & 2 \end{pmatrix} x_3 \succeq 0, \\ & \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} x_1 + \begin{pmatrix} 0 & 3 \\ 3 & 0 \end{pmatrix} x_2 + \begin{pmatrix} 0 & -1 \\ -1 & 2 \end{pmatrix} \succeq 0, \\ & 1.1x_1 + 2x_2 - 4 = 0, \quad -1.2x_2 + 3x_3 - 1 \leq 0 \end{aligned}$$

SDP data: example

[6]: `using` PMO, LinearAlgebra

```
LMI1 = [Symmetric([2 -1 0; 0 2 0; 0 0 2]),  
        0,  
        Symmetric([2 0 -1; 0 2 0; 0 0 2])  
       ]  
LMI2 = [Symmetric([1 0; 0 -1]),  
        Symmetric([0 3; 3 0 ]),  
        0,  
        Symmetric([0 -1; -1 2])  
       ]  
F = PMO.sdp([1,2,3], "inf"),  
      (LMI1, ">=0"),  
      (LMI2, ">=0"),  
      ([1.1,2,0,-4], "=0"),  
      ([0,-1.2,3,-1], "<=0"))
```

SDP data: example with rank 1 matrix

Symmetric matrices of low rank can be used in the Linear Matrix Inequality constraints:

$$\begin{aligned} \inf_{x_1, x_2, x_3} \quad & x_3 \\ \text{s.t.} \quad & \begin{pmatrix} 2 & 1 & 0 \\ 1 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix} x_1 + \begin{pmatrix} 0 & 0 & 0 \\ 0 & 1 & 1 \\ 0 & 1 & 1 \end{pmatrix} x_2 \\ & + \begin{pmatrix} 0 & 0 & 1 \\ 0 & 0 & 1 \\ 0 & 0 & 1 \end{pmatrix} \otimes \begin{pmatrix} 0 & 0 & 1 \\ 0 & 0 & 1 \\ 0 & 0 & 1 \end{pmatrix} x_3 \\ & - \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix} \succeq 0 \end{aligned}$$

```
[7]: LMI1 = [Symmetric([2 1 0; 0 1 0; 0 0 0]),  
           Symmetric([0 0 0; 0 1 1; 0 0 1]),  
           [[0,0,1]],  
           -Symmetric([0 0 0; 0 0 1; 0 0 0])]  
  
F = PMO.sdp(([0,0,1], "inf"), (LMI1, ">=0"))
```

Exercise

👉 Create a PMO data with your favorite example.