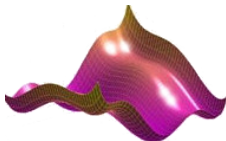


# Polynomial Moment Optimization Database

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General online Julia training, POEMA  
16 April 2021



# Part III - Using the database

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# Using the database

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The PMO data base is loaded as follows:

```
[1]: using PMO
      t = PMO.table()
```

It is a table of triplets (uuid , name, url)

- uuid: a universally unique identifier,
- name: a string containing tags to recover easily the data,
- url: uniform resource location of the data file.

This table only contains references to the PMO data. These data files are available in the local folder `$HOME/.julia/PMO/data`.

## Using the database

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Data can be selected from their `:name` attribute, by regular expressions or matching strings.

```
[2]: t2 = select(t, r"[Mm]otz")
      t3 = select(t, "Motzkin")
```

```
[2]: PMO.DataBase(Table with 3 rows, 3 columns:
```

```
Columns:
```

#	colname	type
1	uuid	String
2	name	String
3	url	String)

To select one column of a table:

```
[3]: select(t2, :name)
```

# Using the database

---

How to recover data in a table:

The  $i^{th}$  entry:

```
[4]: t2[1]
```

Matching strings or regular expressions:

```
[5]: t2[r"Motz."]  
m = t3["Motz"]
```

# Exercise

---

- 1) Find the data which name matches `"Motz.*bounded"`
- 2) Get the `:objective` functions
- 3) Get the vector of `:constraints` polynomial(s)

## Exercise

---

- 1) Find the data which name matches "Motz.\*bounded"
- 2) Get the `:objective` functions
- 3) Get the vector of `:constraints` polynomial(s)

### Solution:

```
[6]: using PMO
      t = PMO.table()
      P = t[r"Motz.*bounded"][1]
      f = P[:objective][1]
      g = [ p[1] for p in P[:constraints] ]
```

## Creating a new data and pushing it

---

We define the data and set its the `:name` and `:author` attributes:

```
[7]: using PMO, DynamicPolynomials
      X = @polyvar x y
      motz = x^4*y^2 + x^2*y^4 + 1 - 3*x^2*y^2

      Motz = PMO.data((motz,"inf"), (2-x^2-y^2, ">=0"))
      Motz[:name] = "Motzkin bounded"
      Motz[:author] = "Joe Test"
```

To push the data to the database, in the file `motzkin_bounded` :

```
[8]: push(t, Motz, file="motzkin_bounded")
```

To remove it from the database:

```
[9]: PMO.rm(t, Motz)
```



## Modifying a data and pushing it

---

```
[10]: using PMO
      t = PMO.table()
      F = t[2]
      F[:version] = "0.0.2"
      push(t,F)
```

Notice that the new version of the data will be committed in the database.

Modifying an existing data should be done with care.

# Adding your own (family of) data

---

- Construct the polynomial constraints and objective functions
- Construct the PMO data
- Specify the name so that it can be recovered easily afterwards
- push the data in the database

## Exercise

---

- 1) Write a function which tests if a data has a polynomial type and has more than 3 two variables (using `getdata(x[:url])`);
- 2) Select all data which satisfy this test (using `select`);
- 3) Write the table in a file `mytable.csv`;
- 4) Define a new table from this file.

## Exercise

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- 1) Write a function which tests if a data has a polynomial type and has more than 3 two variables (using `getdata(x[:url])`);
- 2) Select all data which satisfy this test (using `select`);
- 3) Write the table in a file `mytable.csv`;
- 4) Define a new table from this file.

```
[11]: using PMO; t = PMO.table()
function hasprop(x)
    P = getdata(x[:url])
    return (P[:type]=="polynomial" && P[:nvar] >= 3)
end
tp = select(t, hasprop)
write("mytable.csv", tp)
mt = PMO.table("mytable.csv")
```

# Solving optimization problems

---

The PMO data can be transformed with `vec` into an array of pairs of polynomials and constraints that can be easily used in other functions:

```
[12]: P = t[r"Motz.*bound"][1];  
      vec(P)
```

```
[12]: 2-element Array{Any,1}:  
      (xy2 + x2y - 3x2y2 + 1, "inf")  
      (-x2 - y2 + 2, ">=0")
```

# Solving optimization problems: example with MomentTools & CSDP

```
] add CSDP  
] add https://gitlab.inria.fr/  
  ↪ AlgebraicGeometricModeling/MomentTools.jl
```

```
[13]: using MomentTools, CSDP
```

```
optimizer = CSDP.Optimizer  
v, M = optimize(vec(P), variables(P), 3, optimizer) └  
  ↪ #Moment relaxation at order 3  
get_minimizers(M)
```

# Solving optimization problems: example with MomentTools & CSDP

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get_minimizers(M)
```

...

```
[13]: 2×4 Array{Float64,2}:
```

```
-0.999949  0.999949  -0.999949  0.999949  
0.999949  0.999949  -0.999949  -0.999949
```

# Solving optimization problems: example with TSSOS & MosekTools

---

```
] add MosekTools  
] add https://github.com/wangjie212/TSSOS
```

[14]: `using` TSSOS

```
tssos_first(first.(vec(P)), variables(P), 3)
```



# Solving optimization problems: example with TSSOS & MosekTools

---

```
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] add https://github.com/wangjie212/TSSOS
```

[14]: `using` TSSOS

```
tssos_first(first.(vec(P)), variables(P), 3)
```

[14]: ...  
optimum = 5.3029650589099364e-8  
...